



AI Computing Platform

8F3E1

Datasheet



Version V2.0

Date 2024-02-29

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Document History

Version	Date	Description of Change	Hardware Version
V 1.0	2022-2-28	Preliminary Release	V 1.0
V 2.0	2024-2-29	<ol style="list-style-type: none">1. Change the product manual template;2. Change the product introduction;3. Add interface functional test description.	V 1.0

Hardware Update History

Version	Date	Description of Change
V 1.0	2022-2-28	Initial Version



Electronic components and circuits are very sensitive to electrostatic discharge, although the company will design the main interface on the board card to do anti-static protection design, but it is difficult to do anti-static safety protection for all components and circuits. Therefore, it is recommended that you take ESD safety measures when handling any circuit board component.

ESD safety measures include but are not limited to the following:

1. Put the card in an ESD bag during transportation or storage. Do not take out the card until installation and deployment.
2. Before touching the board, release the static electricity stored in the body: Wear a grounding wrist strap.
3. Operate circuit boards only in electrostatic discharge safe areas.
4. Avoid moving circuit boards in carpeted areas.
5. Avoid direct contact with electronic components on the board through edge contact.

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1 Introduction



The 8F3E1 artificial intelligence computing platform (hereinafter referred to as 8F3E1) is equipped with NVIDIA Jetson AGX Orin/AGX Xavier core modules. It can provide up to 275 TOPS of computing power, which can be widely used in education, industrial automation, smart city and other scenarios. With a wealth of external interface, internal interface devices are wide temperature model.

8F3E1 internal reserve 2280 size M.2 Key M interface, full length miniPCIe interface, PCIe interface, expandable USB3.0 signal, SSD memory card, SATA signal, 4G communication module, all kinds of video acquisition/output card, AD acquisition card, multi-serial port card, sound acquisition/output card, multi-function IO card, etc.

2 Specifications

	Feature
Carrier Board	Y-C8
Module	NVIDIA Jetson AGX Orin / AGX Xavier Series Modules
Temperature	-20 ~ +65°C
Dimensions (W×H×D)	198mm*197mm*45mm (Including I/O ports and mounting holes)
Weight	1340 g

Power Supply	Spec
Input Type	DC
Input Voltage	+12 V

I/O Ports

Interface	Quantity	Interface	Quantity
USB3.0 Type-A	2	Micro USB	1
RJ45	2	HDMI	1
RS232(DB9)	2	Micro SD Card Slot	1
CAN	2	GPIO	4

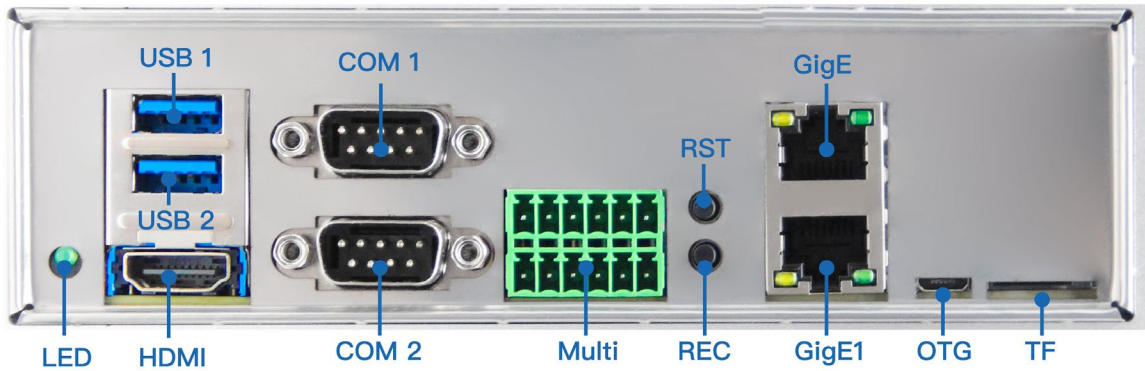
* When used with the Jetson AGX Xavier module, only one USB3.1 is available and the rest USB2.0. One of the RJ45 network ports is not standard.

NVIDIA Jetson Series Modules

Technical Specifications

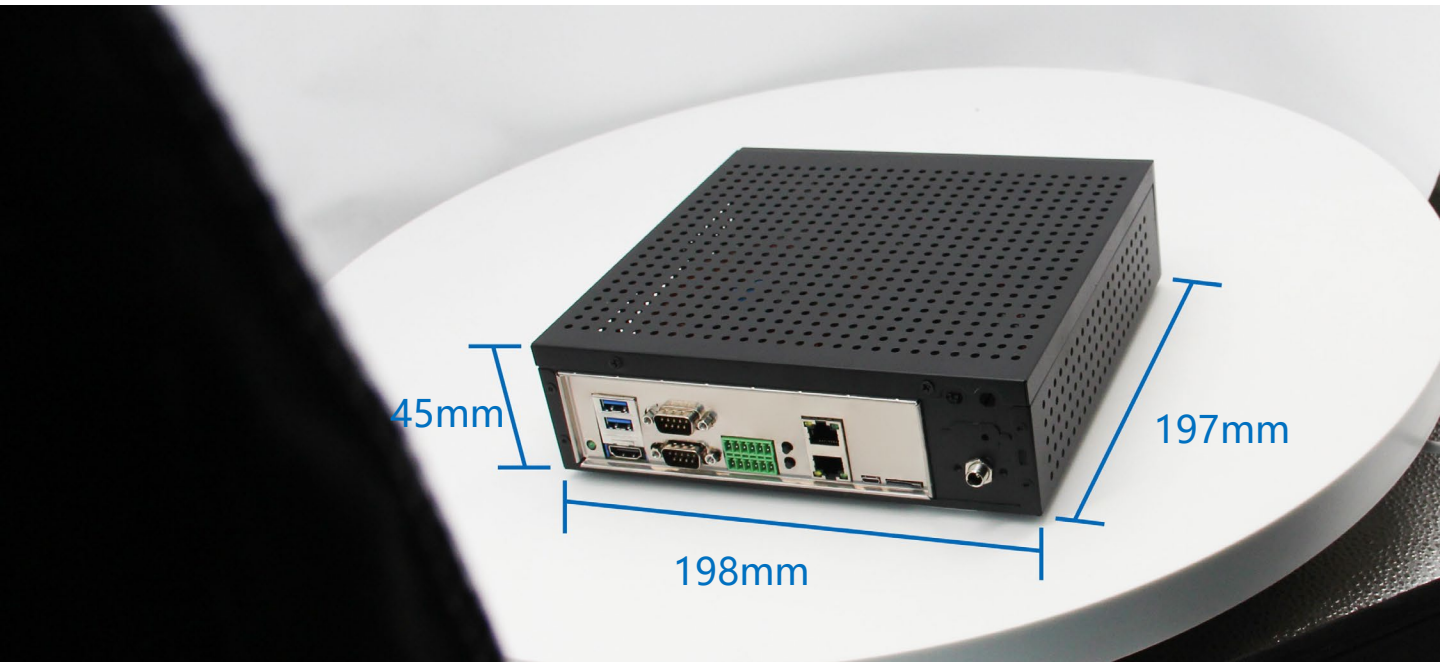
Module	Jetson AGX Xavier 32GB	Jetson AGX Xavier 64GB	Jetson AGX Orin 32GB	Jetson AGX Orin 64GB
AI Performance	32TOPS		200 TOPS	275 TOPS
GPU	512-core NVIDIA Ampere architecture GPU with 64 Tensor Cores		1792-core NVIDIA Ampere architecture GPU with 56 Tensor Cores	2048-core NVIDIA Ampere architecture GPU with 64 Tensor Cores
CPU	8-core NVIDIA Carmel Arm® v8.2 64-bit CPU 8MB L2 + 4MB L3		8-core Arm® Cortex®-A78AE v8.2 64-bit CPU 2MB L2 + 4MB L3	12-core Arm® Cortex®-A78AE v8.2 64-bit CPU 3MB L2 + 6MB L3
Memory	32GB 256-bit LPDDR4x 136.5GB/s	64GB 256-bit LPDDR4x 136.5GB/s	32GB 256-bit LPDDR5 204.8 GB/s	64GB 256-bit LPDDR5 204.8 GB/s
Storage	32GB eMMC 5.1		64GB eMMC 5.1	
Video Encode	4x 4K60 (H.265) 8x 4K30 (H.265) 16x 1080p60 (H.265) 32x 1080p30 (H.265)		1x 4K60 (H.265) 3x 4K30 (H.265) 6x 1080p60 (H.265) 12x 1080p30 (H.265)	2x 4K60 (H.265) 4x 4K30 (H.265) 8x 1080p60 (H.265) 16x 1080p30 (H.265)
Video Decode	2x 8K30 (H.265) 6x 4K60 (H.265) 12x 4K30 (H.265) 26x 1080p60 (H.265) 52x 1080p30 (H.265)		1x 8K30 (H.265) 2x 4K60 (H.265) 4x 4K30 (H.265) 9x 1080p60 (H.265) 18x 1080p30 (H.265)	1x 8K30 (H.265) 3x 4K60 (H.265) 7x 4K30 (H.265) 11x 1080p60 (H.265) 22x 1080p30 (H.265)
Power	10W - 30W		15W - 40W	15W - 60W

3 External I/O Ports



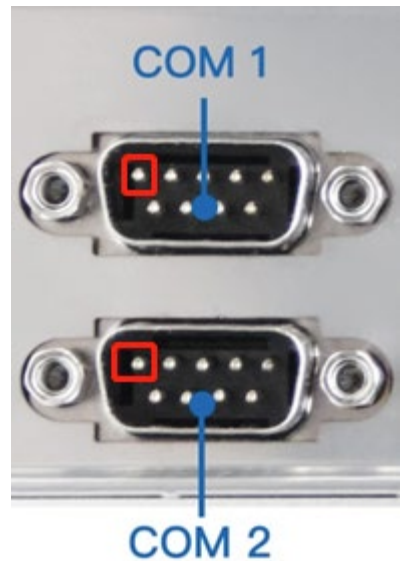
Sign	Function	Sign	Function
TF	Micro SD Card Slot	HDMI	Type-A HDMI Connector
Gige	RJ45Jack(Non standard part)	Gige1	RJ45 Jack(10/100/1000Mbps Ethernet)
LED	Power LED	Multi	Multi-function IO Interface
COM1/ COM2	RS232 Serial Port	USB1/ USB2	Type A USB 3.0 Connector
RST	Reset Button	REC	Recovery Button
OTG	Type-B Micro USB Connector (Only use to flash system)		

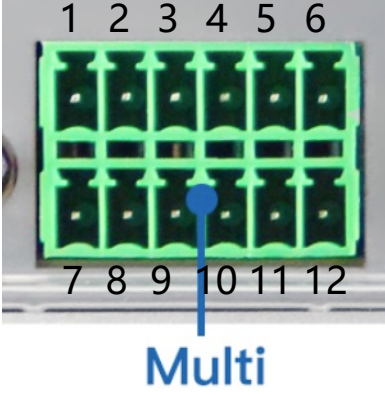
4 All-Round Display



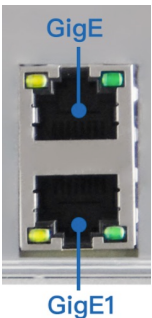
5 Connector Description

DB9 Connector (COM1/COM2)				
Function	RS232 Serial Port			
Sign	COM1/COM2			
Type/Model	DB9 Connector			
Pin definition	Pin 1 position: right picture identification.			
	Pin	Signal	Pin	Signal
	1	NC	2	RX_RS232
	3	TX_RS232	4	NC
	5	GND	6	NC
	7	NC	8	NC
	9	NC	10	NC
Device Names		AGX ORIN	AGX Xavier	
	COM1	/dev/ttyTHS4	/dev/ttyTHS1	
	COM2	/dev/ttyTHS0	/dev/ttyTHS0	



Multi-function IO Interface																																
Function	CAN\GPIO																															
Sign	Multi																															
Pin definition	<table border="1"> <thead> <tr> <th>引脚</th> <th>信号</th> <th>引脚</th> <th>信号</th> </tr> </thead> <tbody> <tr> <td>1</td> <td>CAN1_H</td> <td>2</td> <td>3.3V</td> </tr> <tr> <td>3</td> <td>CAN1_L</td> <td>4</td> <td>GND</td> </tr> <tr> <td>5</td> <td>GND</td> <td>6</td> <td>GPIO08</td> </tr> <tr> <td>7</td> <td>CAN0_H</td> <td>8</td> <td>GPIO09</td> </tr> <tr> <td>9</td> <td>CAN0_L</td> <td>10</td> <td>GPIO17</td> </tr> <tr> <td>11</td> <td>GND</td> <td>13</td> <td>GPIO27(PWM)</td> </tr> </tbody> </table>	引脚	信号	引脚	信号	1	CAN1_H	2	3.3V	3	CAN1_L	4	GND	5	GND	6	GPIO08	7	CAN0_H	8	GPIO09	9	CAN0_L	10	GPIO17	11	GND	13	GPIO27(PWM)			
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RJ45 (Gige/Gige1)	
Function	10/100/1000Mbps Ethernet
Sign	Gige/Gige1
Type/Model	RJ45 Jack
Explain	Gige network port is not standard, only Gige1 is available by default.



6 Ordering Information

Order Type	Function
8F3E1	Interface extension carrier board for NVIDIA® Jetson™ ORIN NX/ORIN Nano series modules
If you need to add other functional modules, please confirm the plan with our sales and technical personnel in advance.	

E-commerce Platform

Taobao Store Address: <https://shop333807435.taobao.com/>

Jingdong Store Address: <https://mall.jd.com/index-11467104.html?from=pc>

Ali International Station Address: <https://plink-ai.en.alibaba.com/>

7 Recovery Mode

Jetson core module can work in normal mode and Recovery mode. In Recovery mode, it can perform file system update, kernel update, Bootloader/UEFI update, BCT update and other operations.

To enter the Recovery mode, perform the following steps:

Power off the system.

Use a Micro-USB cable to connect the Micro-USB port (OTG) of the 8F3E1 to the Jetson development host USB port.

The Jetson development host should be Ubuntu18.04 or Ubuntu20.04 based on X86 architecture.

Press the Recovery key (REC) to power the system. Hold down the Recovery key (REC) for more than 3 seconds, and then release the Recovery key (REC).

When the system enters Recovery mode, you can perform subsequent operations.

8 Method of Application

- Make sure all external system voltages are turned off.
- Install necessary external cables. (For example: the display cable to connect to the HDMI monitor, the power input cable to power the system, the USB cable to connect the keyboard and mouse...)
- Connect the power cord to the power supply.
- 8F3E1 is automatically powered on by default. It can also be set to switch start. Please consult our sales and technical personnel for specific methods.

9 GPIO Test

8F3E1 leads to the 4-way GPIO of the Jetson core modules. Programmable output voltage 3.3V, please note that the input voltage does not exceed 3.3V.

Take the AGX ORIN module, L4T35.3.1, GPIO08 as an example:

The content after the '#' in the following command is a comment and does not need to be added when executing the command.

- `sudo su`
- `echo 325 > /sys/class/gpio/export # Enable GPIO (Or initialize GPIO)`
- `echo out > /sys/class/gpio/PBB.01/direction`

`#Set the GPIO input and output directions to out or in.`

- `echo 1 > /sys/class/gpio/PBB.01/value`
`# Set the GPIO output high/low level to 1 for high and 0 for low.`

`#The preceding absolute path name is based on the actual path name generated after GPIO is enabled.`

`# When set to the input state, you can only read values. When set to the output state, you can read and write values.`

- `cat /sys/class/gpio/PBB.01/value #Get GPIO value.`

`# The output state can be measured using a multimeter to measure the voltage between the specific lead heel GND.`

10 CAN Test

8F3E1 is equipped with two CAN signals when it is equipped with Jetson module. During test, connect the CAN_H of the device to the CAN_H of the device under test and the CAN_L to the CAN_L of the device under test.

The test command is as follows:

- `sudo apt-get install busybox can-utils`

#Writes the specified value to a register

Different modules need to write to the address of the register, and the value written is inconsistent. See the links at the end of this section for details.

- `sudo busybox devmem 0x0c303020 w 0x458`
- `sudo busybox devmem 0x0c303018 w 0x400`
- `sudo busybox devmem 0x0c303010 w 0x458`
- `sudo busybox devmem 0x0c303008 w 0x400`
- `sudo modprobe can` #Load the CAN bus subsystem support module
- `sudo modprobe can_raw` #Load the original CAN protocol module.
- `sudo modprobe mttcan` #Load CAN interface support
- `sudo ip link set can0 type can bitrate 500000`
#Set CAN0 bit rate to 500k bps
- `sudo ip link set can1 type can bitrate 500000`
#Set CAN1 bit rate to 500k bps
- `sudo ip link set up can0` #Open CAN0
- `sudo ip link set up can1` #Open CAN1
- `candump can0` #Set CAN0 to receive
- `cansend can1 1F223344#1122334455667788`

Open another terminal to send data through CAN1. After sending, there will be data echo at the receiving end of CAN0.

See links for different module register values:

[Controller Area Network \(CAN\) — Jetson Linux Developer Guide documentation](#)

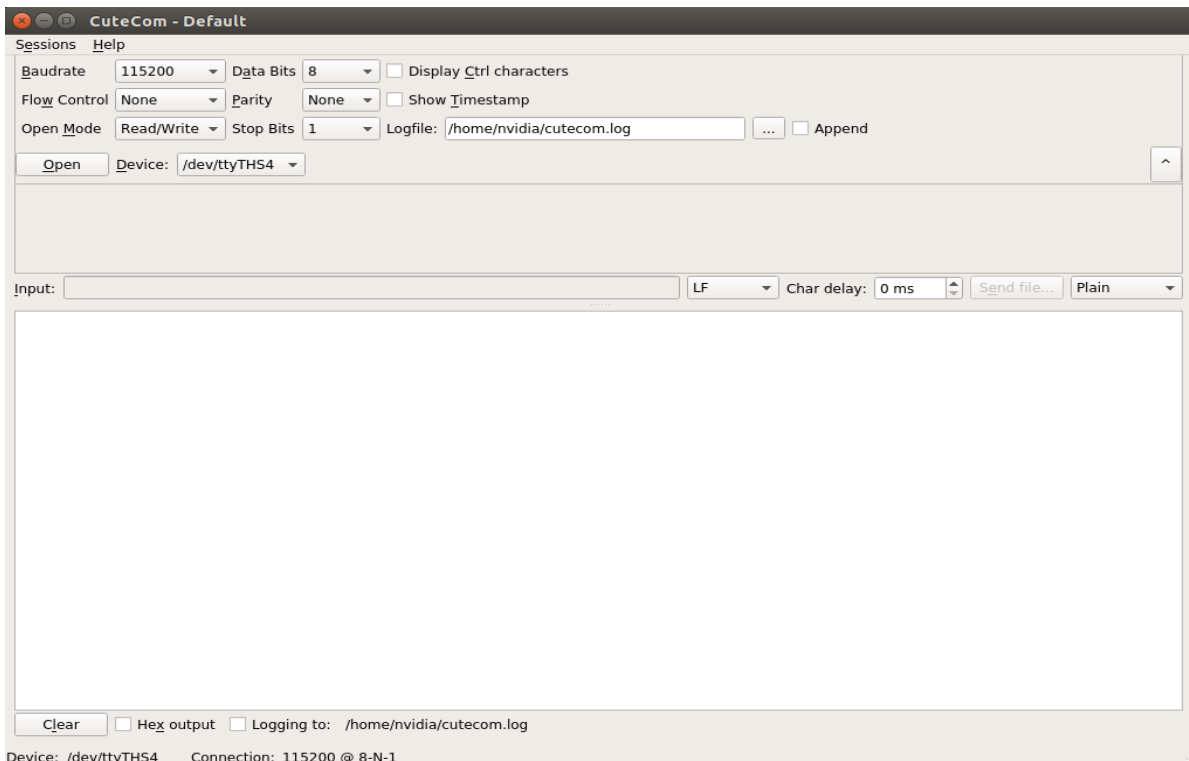
[nvidia.com](https://www.nvidia.com)

11 Serial Port Test

8F3E1 is equipped with two RS232 serial ports as standard when it is paired with Jetson module, which can be used for self-collecting test of a single serial port and interconnection test of two serial ports. The command is as follows:

- `sudo apt-get install cutecom` #Install the serial port test tool
- `sudo cutecom` # For a single-serial port test, you only need to open one cutecom interface on each terminal. For a two-serial port connection test, use two terminals and open two cutecom interfaces.
- When testing a single serial port, connect the RX of a single serial port to the TX. When the two serial ports are connected, the RX of UART1 is connected to the TX of UART2, and the TX of UART1 is connected to the RX of UART2.

The interface of the serial port test tool cutecom is as follows:



12 Special Instructions

- Initial system username: **nvidia** , password: **nvidia** , no password su. If root permissions are required, use sudo to grant permissions, or use sudo su to access the root user.
- The pre-installed system is pure by default and does not contain Jetpack software. You can use the following command to install the software. Do not replace or modify the default software source before installation:
 - `sudo apt-get update`
 - `sudo apt-get install nvidia-jetpack`
- It can also be installed over the network using SDKmanager software.
- For more information please refer to [:Jetson wiki \(plink-ai.com\)](http://jetson.wiki(plink-ai.com))